

LA-UR-20-29455

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Title: The Wide Power and Applicability of Robotics

Author(s): Grow, David Isaac

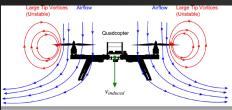
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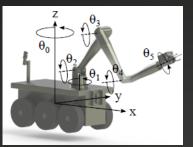


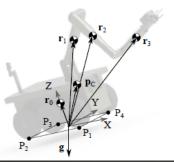


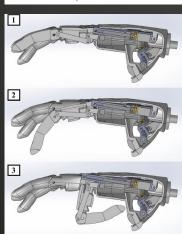














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The Wide Power and Applicability of Robotics

How can you recognize the hidden robots all around you? What is the ideal human-robot relationship?

How can robots protect people from dangerous situations?

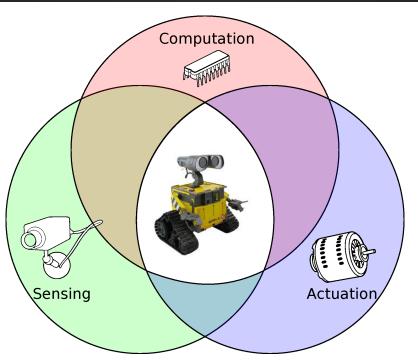


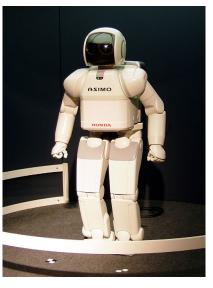
Dr. David Grow

11/16/20

















Robots as Tools for Rehabilitation and Assistance



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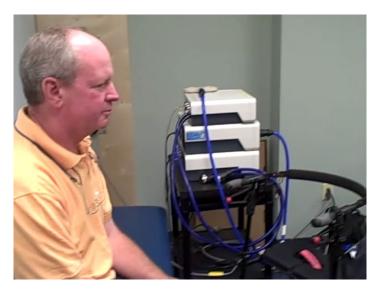
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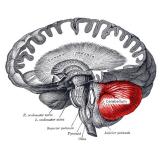


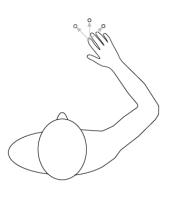


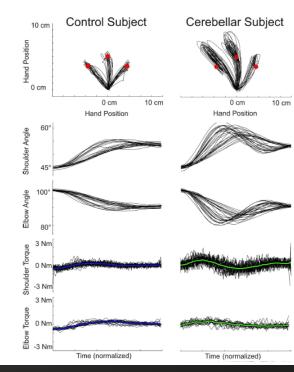


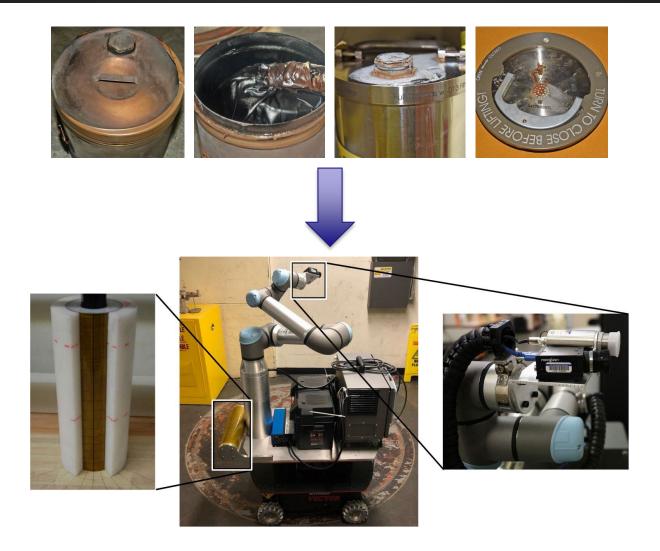










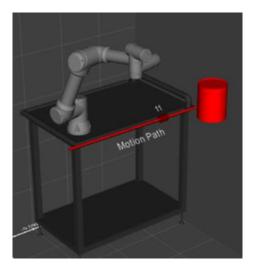


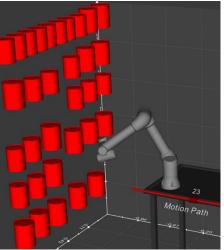








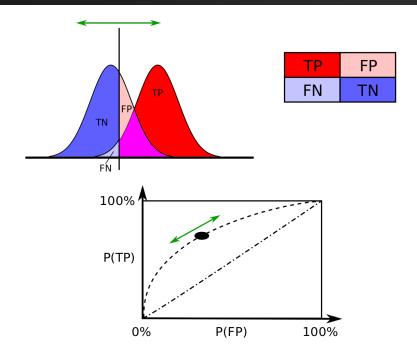






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Containers were damaged with denting, bulging, corrosion, and mock dis-charge residue. Damage was imposed with three levels of severity. level I (minor damage), level II(significant damage), and level III (catastrophic damage resulting in a containment breach). Level I targeted a level of damage that was just evident to the naked eye. An example of this is illustrated in Fig 27 (b,c,f). Minor note - the machine learning was not applied to corrosion results for a number of reasons.

Performance relative to Level I damage is probably the best way to address the question. We don't know what level of detection accuracy is "needed", but we can certainly aim to meet or exceed human performance. Better than the percentages you reference, I'd point you to Figures 29 and 30 (copy included herein). Reading across the top row of each:

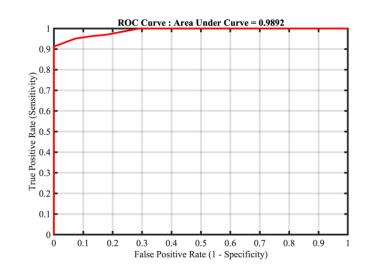
A human inspector correctly identified 13 cases, miscategorized one (a trivial point), and altogether missed 7

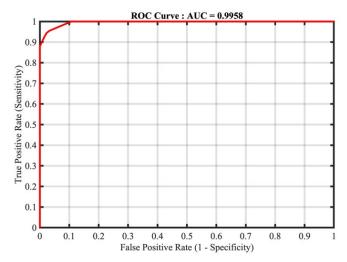
The AI / robotic system correctly classified them all.

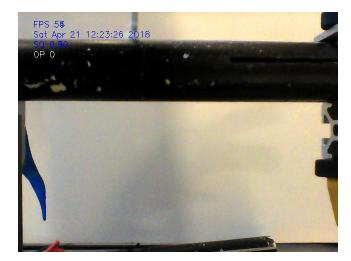
The results weren't as impressive with respect to Level II damage, oddly, with 3 false negatives .

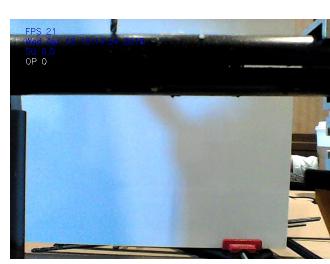
Also results were mediocre with respect to residue false negatives (10) and false positives (4).

Thats said, even in these last two cases, those performance values were better than human.





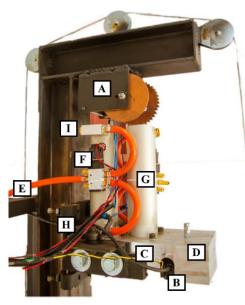


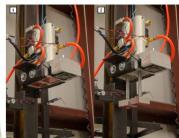












- A: Dock winch
- B: Electromagnet
- C: Limit switch
- D: Docking station
- E: Air reservoir line
- F: solenoid valve
- G: Pneumatic solenoid
- H: Locking clamps I: Adjustable quick valve
- Pneumatic cylinders disengaged
 Pneumatic cylinders triggered

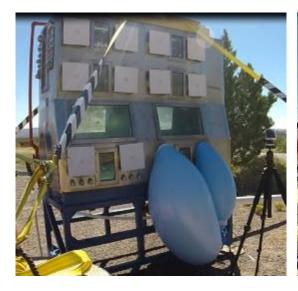
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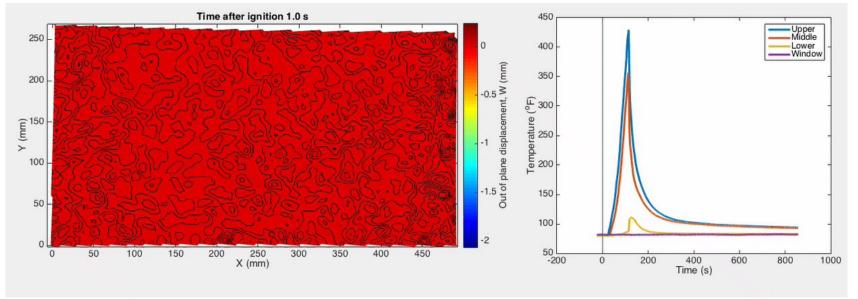


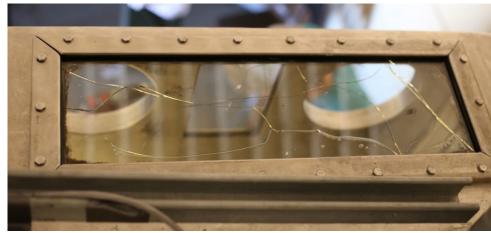




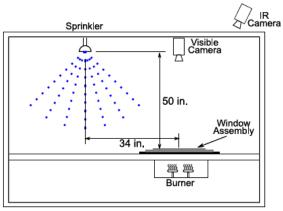


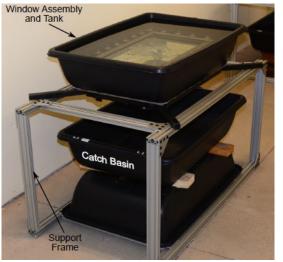


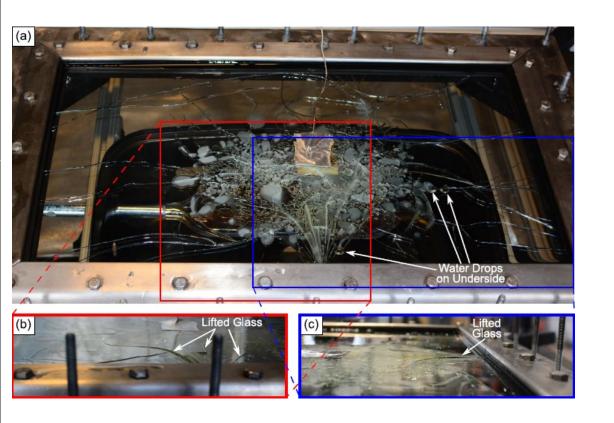
















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